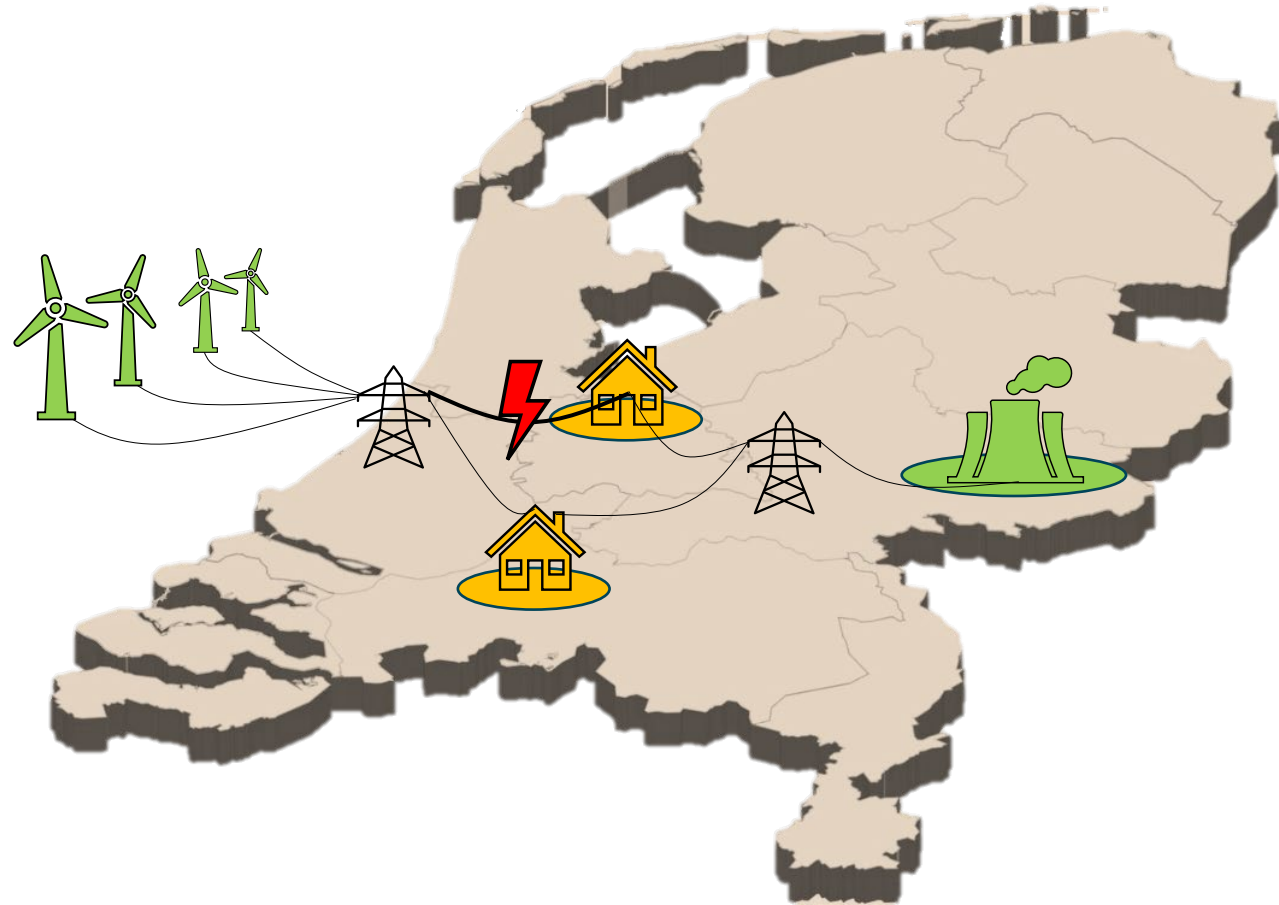


# Constraint-Driven Deep Learning for N-k Security Constrained Optimal Power Flow

Bastien Giraud, Ali Rajaei, Jochen L. Cremer



# Acknowledgement



Bastien Giraud



Ali Rajaei

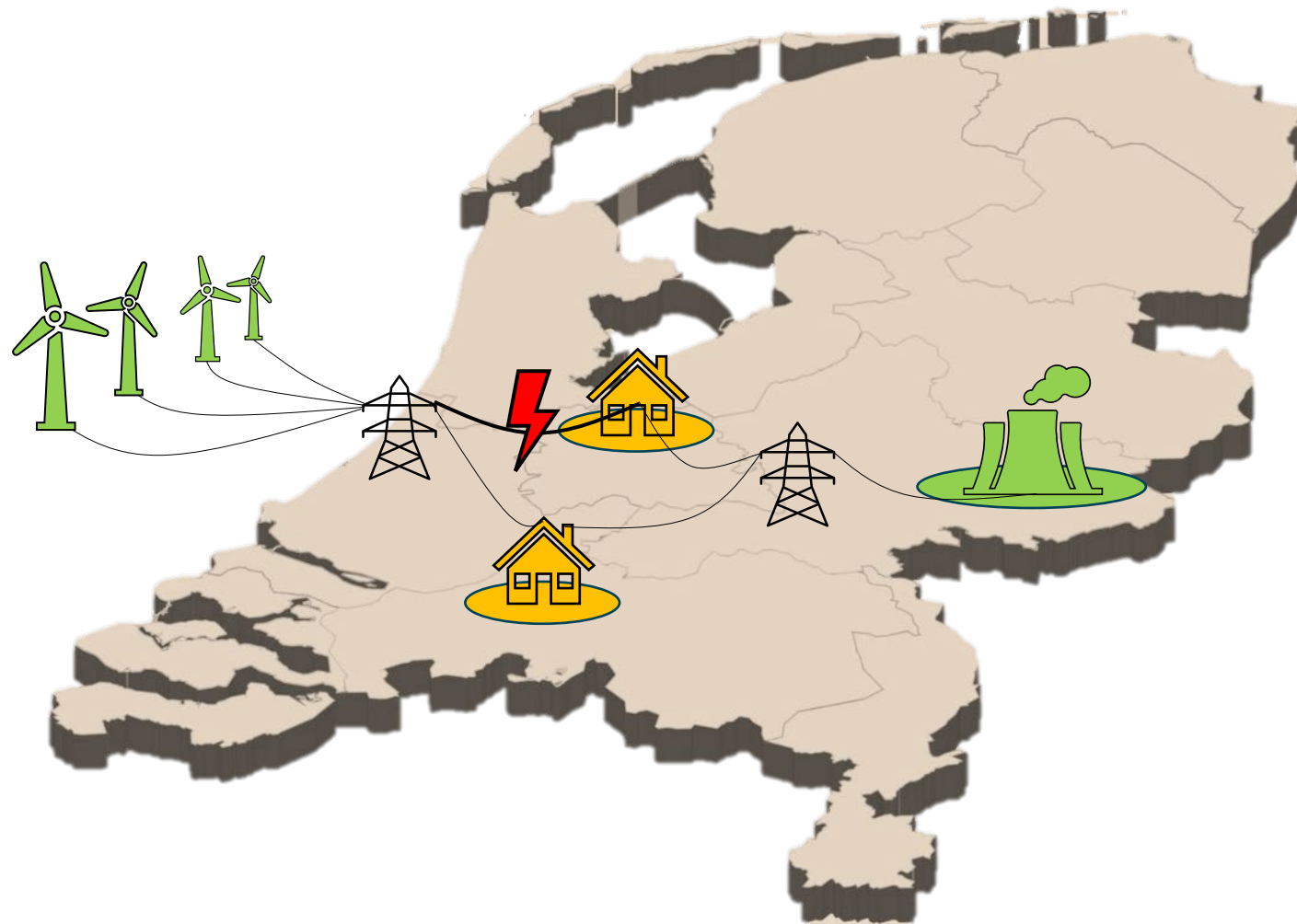
Web: <https://www.tudelft.nl/ai/delft-ai-energy-lab>

## Reference

- Bastien Giraud, Ali Rajaei, Jochen L. Cremer “Constraint-Driven Deep Learning for N-k Security Constrained Optimal Power Flow”, in review *IEEE Power System Computing Conference 2024*
- Code: <https://github.com/TU-Delft-AI-Energy-Lab>

# N-1 Security

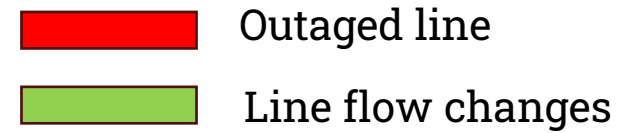
Generation  $P_G$   
Demand  $P_D$



# Line outage distribution factors

- Line outage distribution factor (LODF)
- Linear sensitivity factor
- Indicates change of flow over line when another line is in outage

$$F^c = F^0 + LODF_{N-k} \times F^0$$



# Security constrained optimal power flow (SCOPF)

Objective: minimize cost

Constraints: In = out

Generator limits

Line flow limits

Contingency Constraints: Line flow limits

$$\min_{n \in \Omega^G} \sum c_n P_{G_n}$$

$$\mathbf{B} \cdot \boldsymbol{\delta} = \mathbf{P}_G - \mathbf{P}_D$$

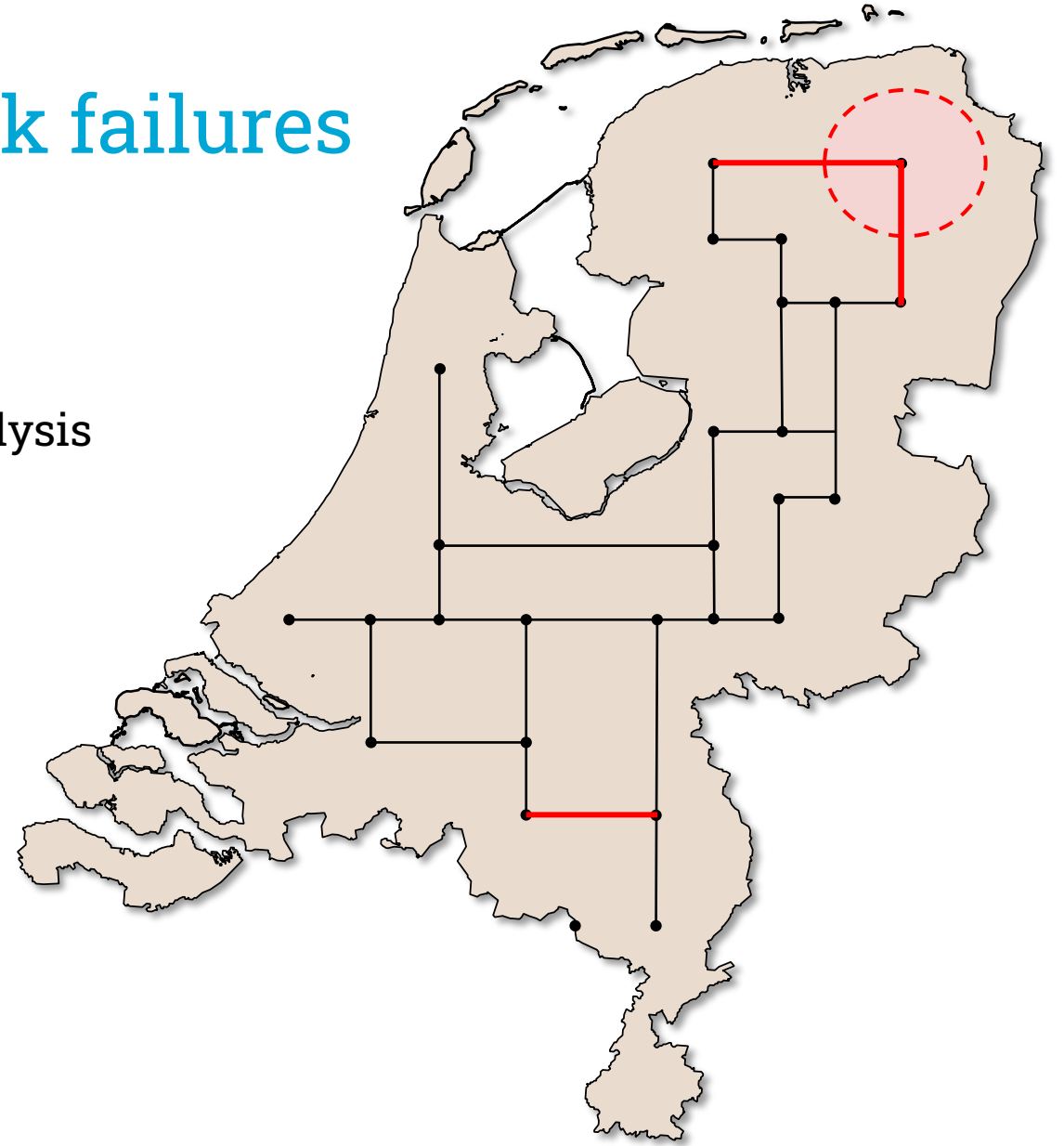
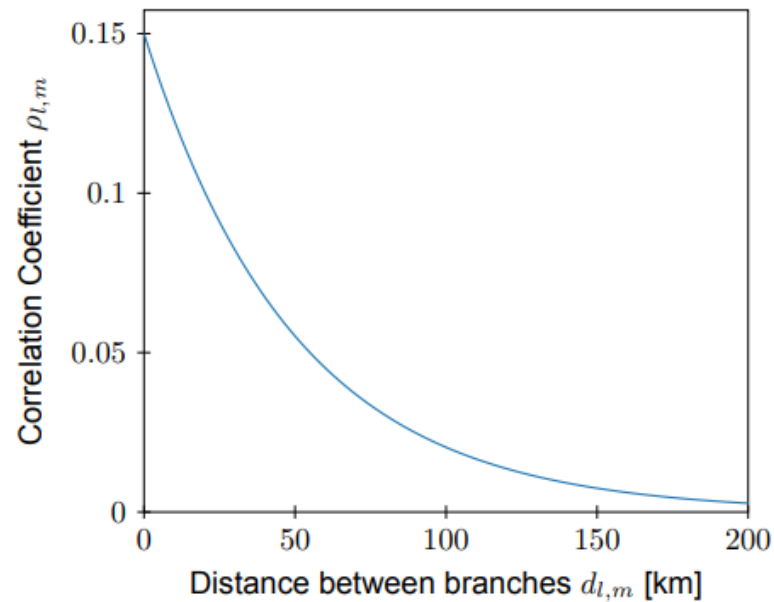
$$P_{G_n}^{min} < P_{G_n} < P_{G_n}^{max} \quad \forall n \in \Omega^G$$

$$F_l^{min} < F_l < F_l^{max} \quad \forall l \in \Omega^L$$

$$F_l^{min} < F_l^c < F_l^{max} \quad \forall l \in \Omega^L, \forall c \in \Omega^C$$

# Probabilistic security for N-k failures

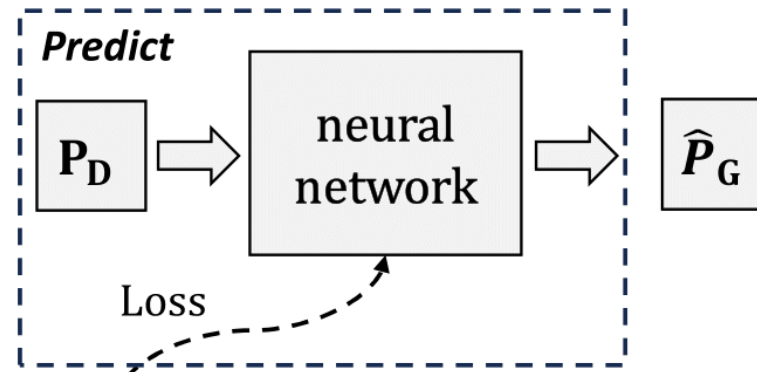
- Compute probabilities of all contingencies
- Spatial correlation between line outages
- Compute joint probabilities using a copula analysis



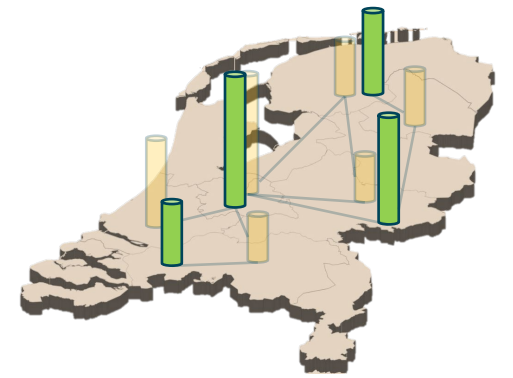
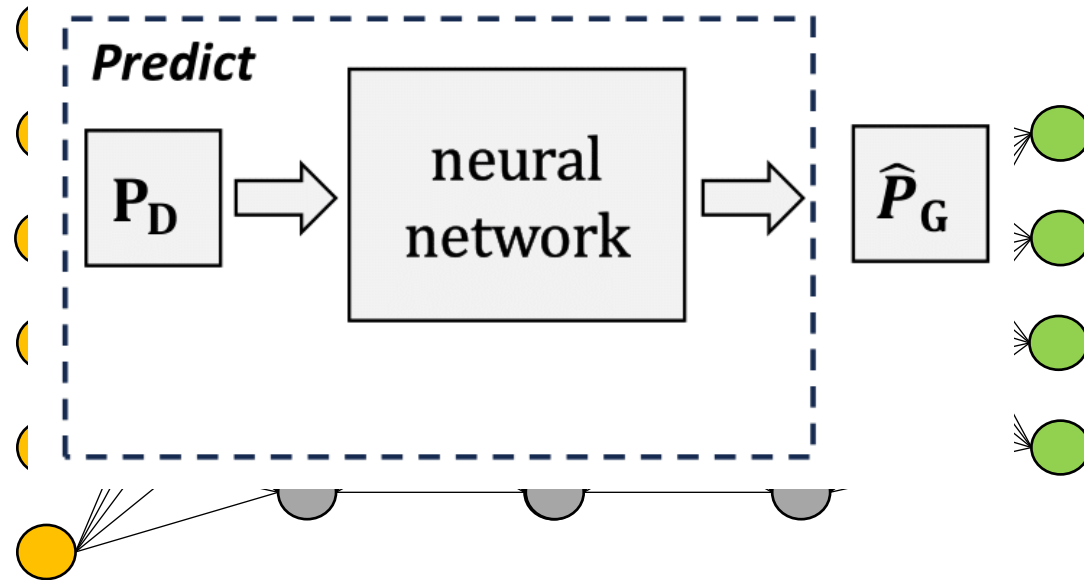
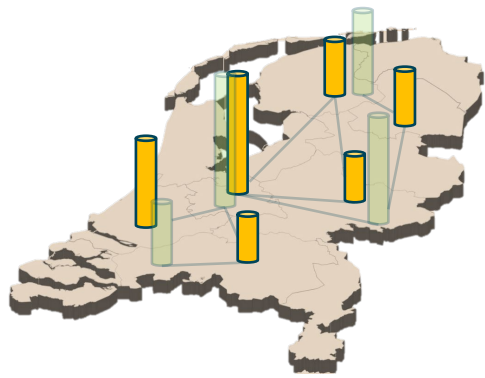
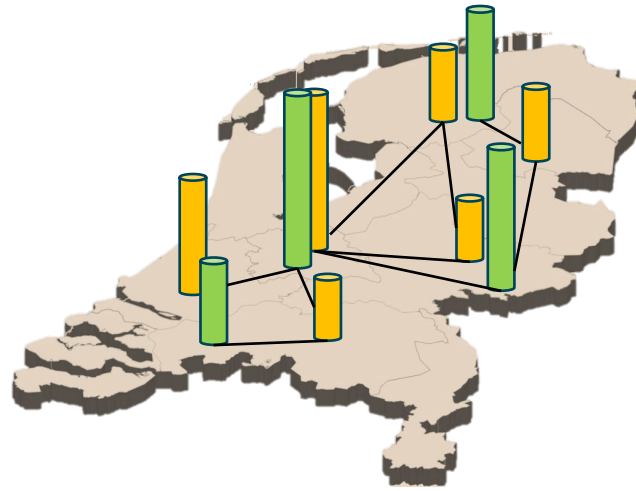
# Proposed Constraint-Driven Deep Learning Approach

- Main advantage: constraint-driven so no labeled data needed
- Never actually solve an SCOPF

1. Predict
2. Feasibility Restoration
3. Post-contingency



# 1. Predict



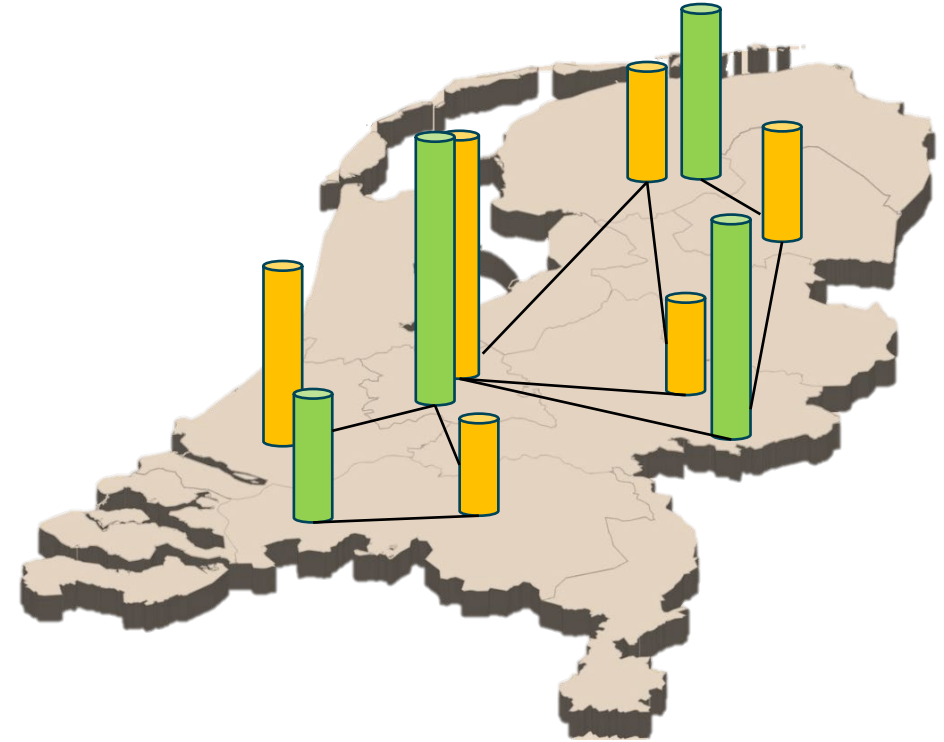


## 2. Feasibility Restoration

- With  $\hat{P}_{G_n}$  compute predicted line flow  $\hat{F}_l^0$
- Prediction might be outside physically infeasible

$$g(x): \quad P_{G_n}^{min} < P_{G_n} < P_{G_n}^{max} \quad \forall n \in \Omega^G$$
$$F_l^{min} < F_l < F_l^{max} \quad \forall l \in \Omega^L$$

$$h(x): \quad B \cdot \delta = P_G - P_D$$

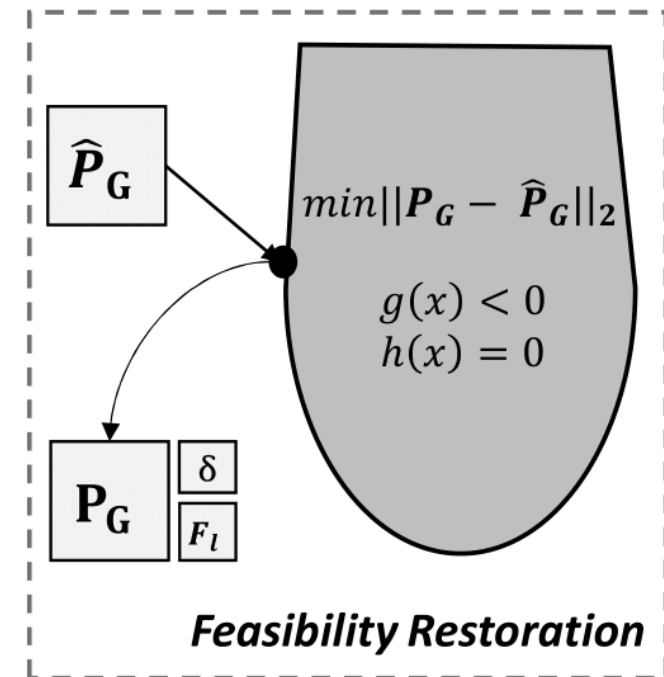


## 2. Feasibility Restoration

- Map prediction to feasible region
- Minimize distance between prediction and base case feasible region

$$g(x): \quad P_{G_n}^{min} < P_{G_n} < P_{G_n}^{max} \quad \forall n \in \Omega^G$$
$$F_l^{min} < F_l < F_l^{max} \quad \forall l \in \Omega^L$$

$$h(x): \quad B \cdot \delta = P_G - P_D$$



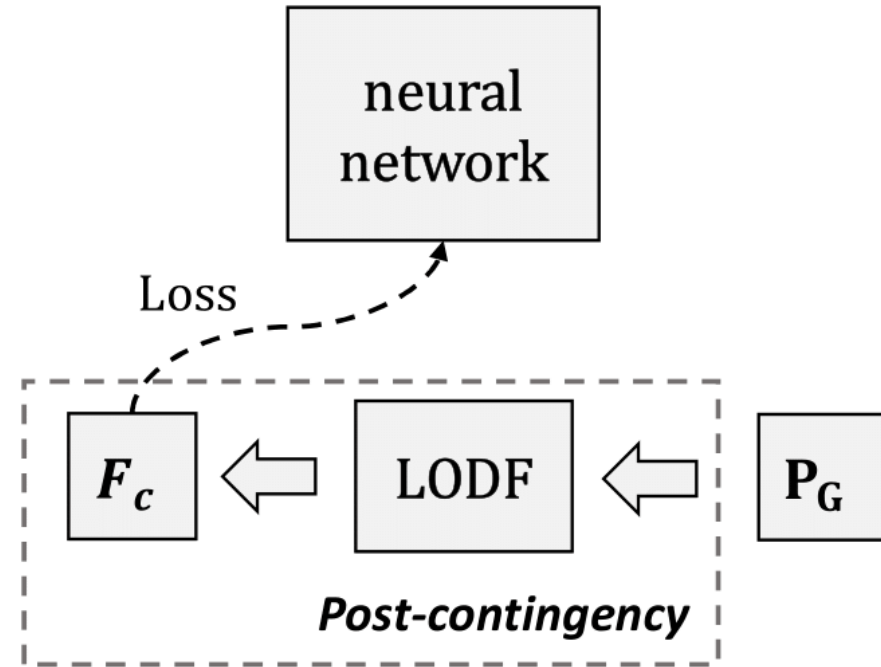
### 3. Post-Contingency

- Compute post-contingency flows with LODFs

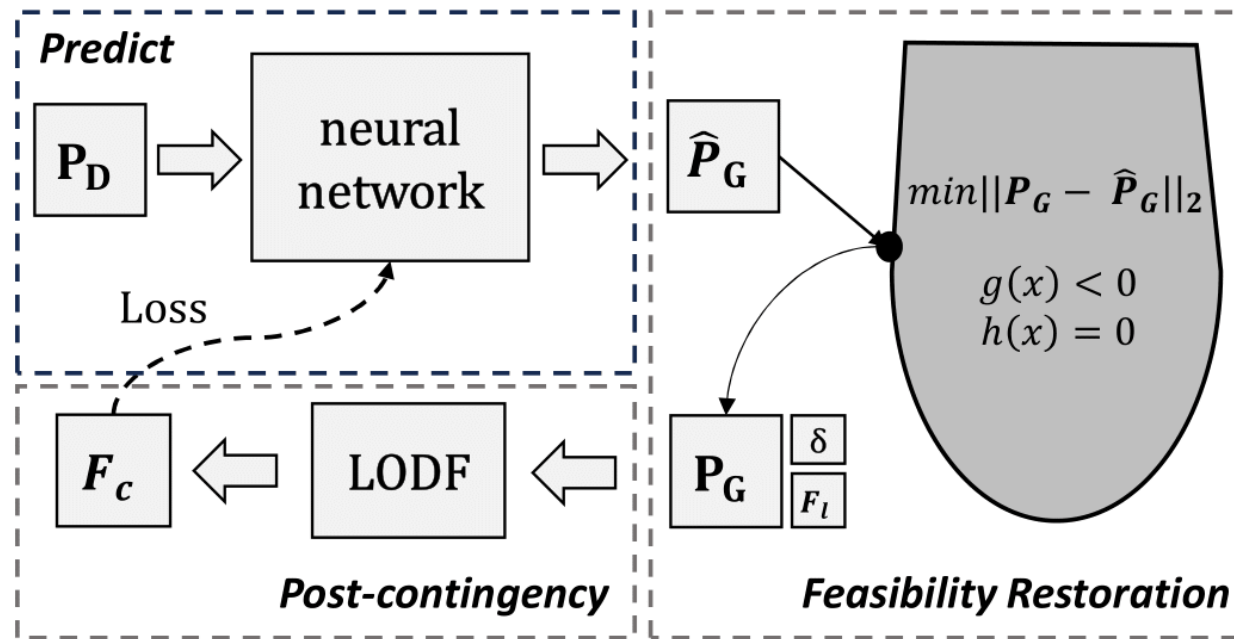
$$F^c = F^0 + LODF_{N-k} \times F^0$$

- Check for post-contingency violations

$$F_l^{min} < F_l^c < F_l^{max} \quad \forall l \in \Omega^L, \forall c \in \Omega^C$$

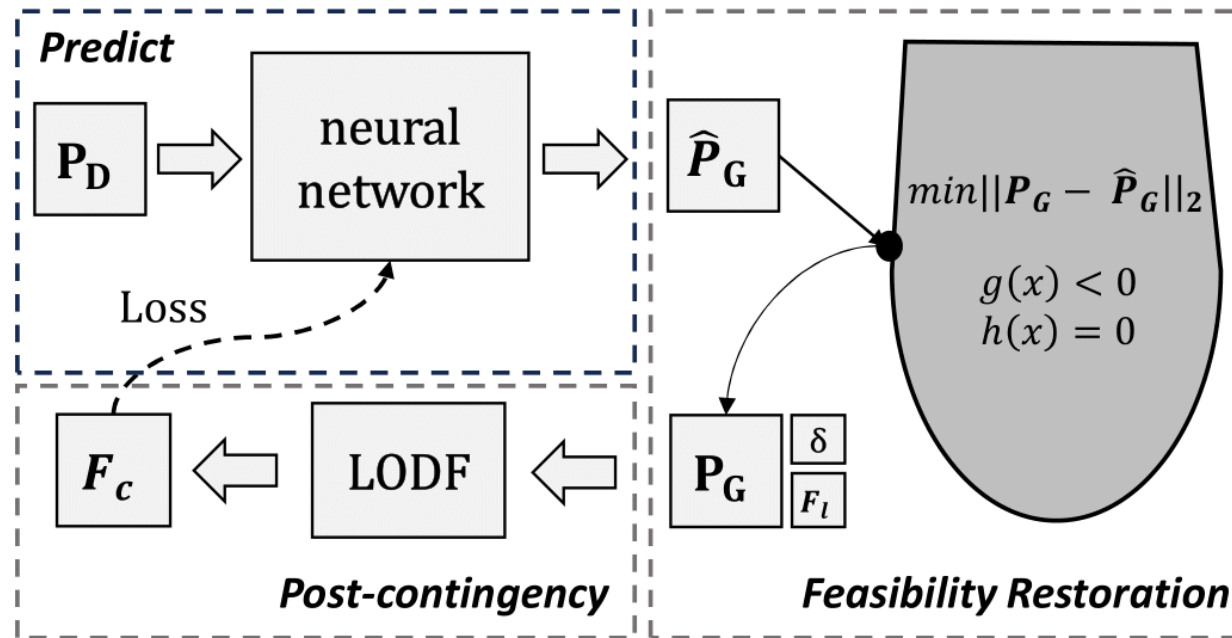


# Proposed Constraint-Driven Learning Approach



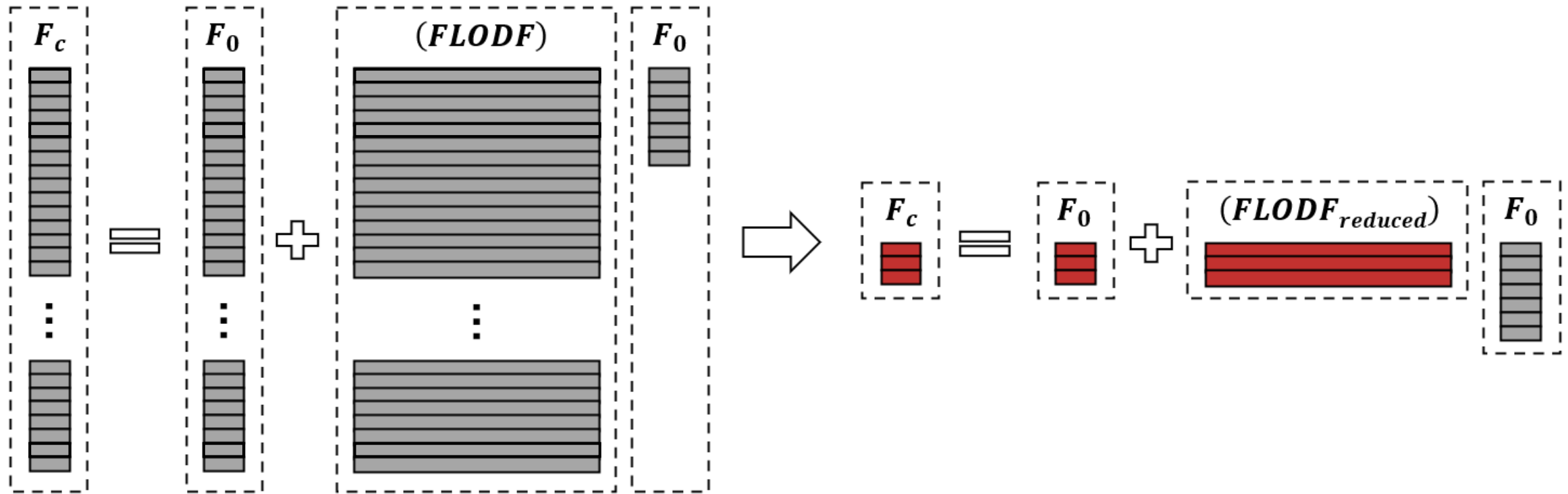
$$Loss = \lambda_c \sum P_G c_G + \lambda_0 \|ReLU(|\hat{F}^0| - F^{max})\|_1 + \lambda_1 \|ReLU(|F^c| - F^{max})\|_1 + \lambda_2 \|\sum \hat{P}_G - \sum P_D\|_1$$

# Probabilistic security



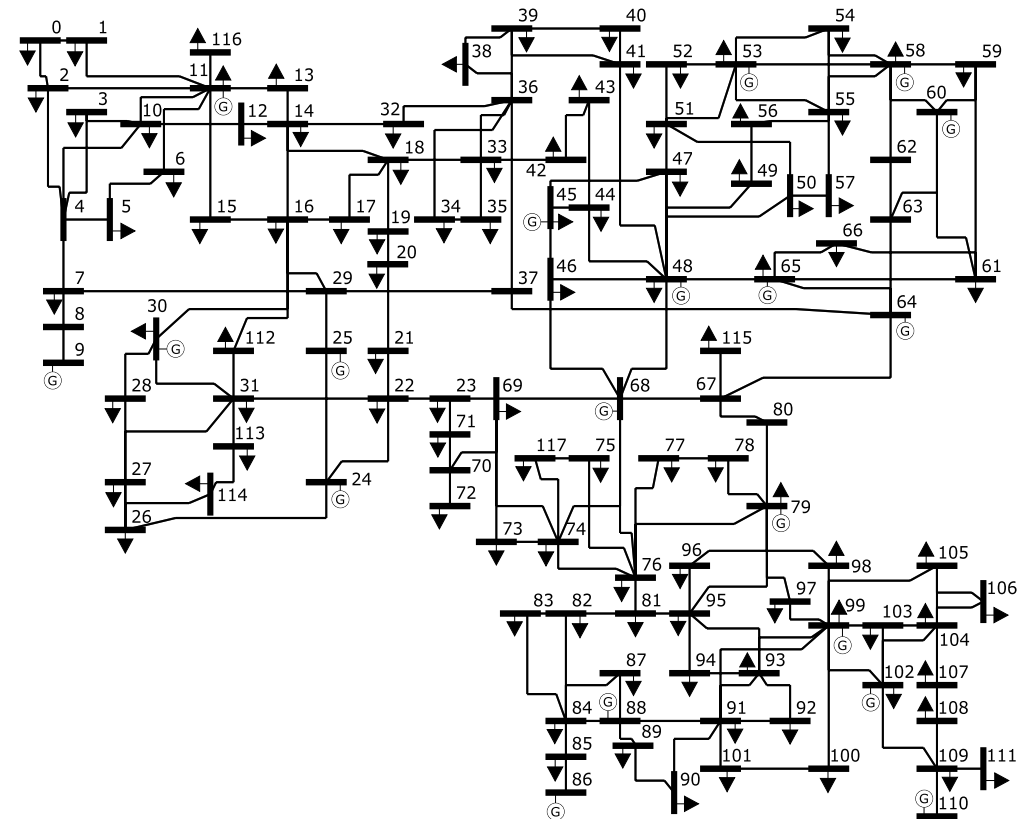
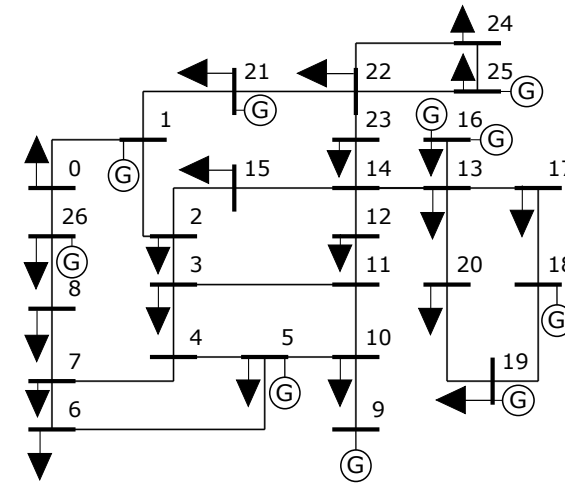
$$Loss = \lambda_c \sum P_G c_G + \lambda_0 \|ReLU(|\hat{F}^0| - F^{max})\|_1 + \lambda_1 \|\pi_{N-k} \cdot ReLU(|F^c| - F^{max})\|_1 + \lambda_2 \|\sum \hat{P}_G - \sum P_D\|_1$$

# Computational graph to address combinatorial complexity

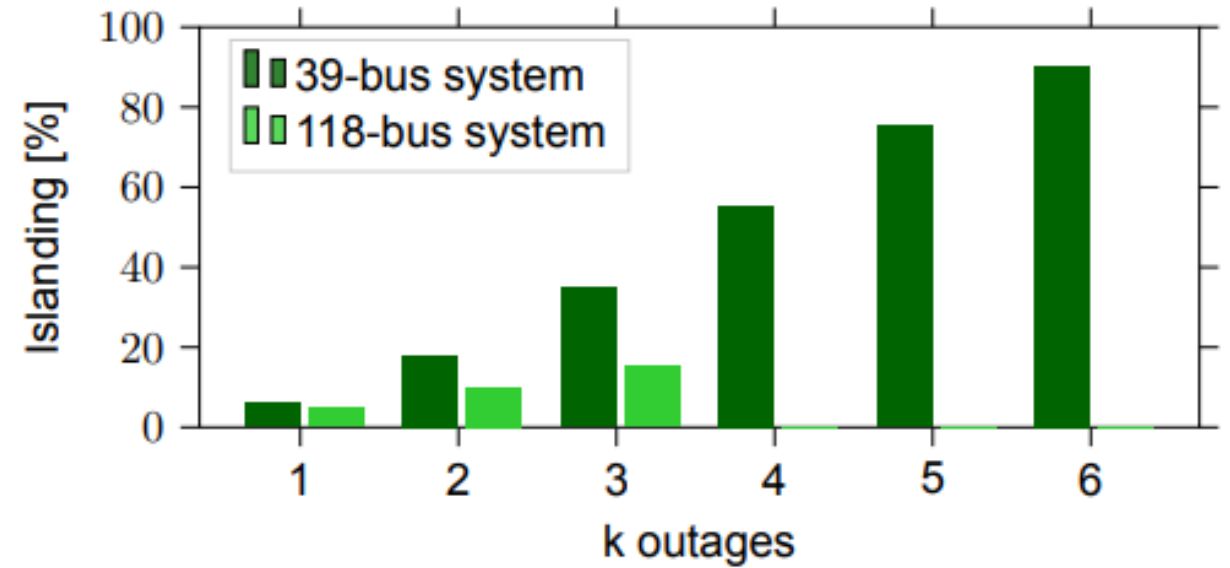
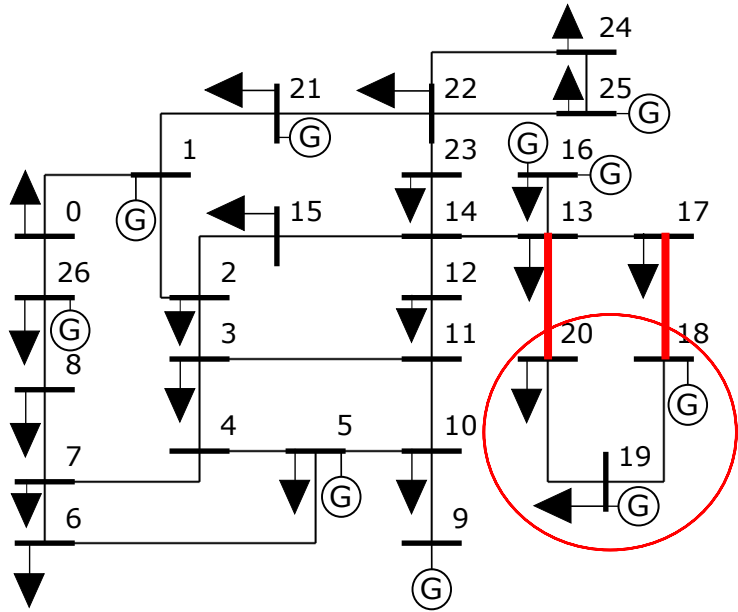


# Case studies

- 39-bus and 118-bus test systems
- $k = \{1,2,3\}$
- Baseline: iterative contingency screening with LODFs



# Islanding

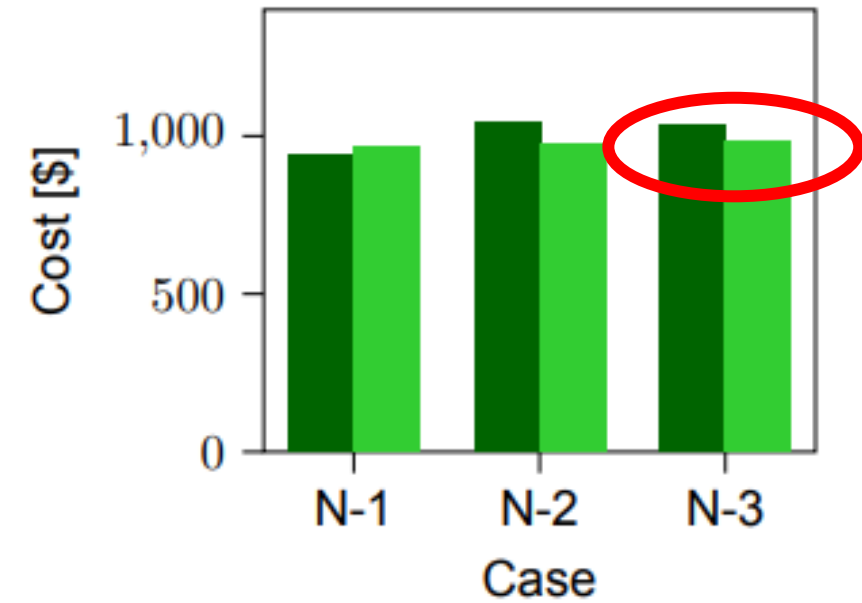
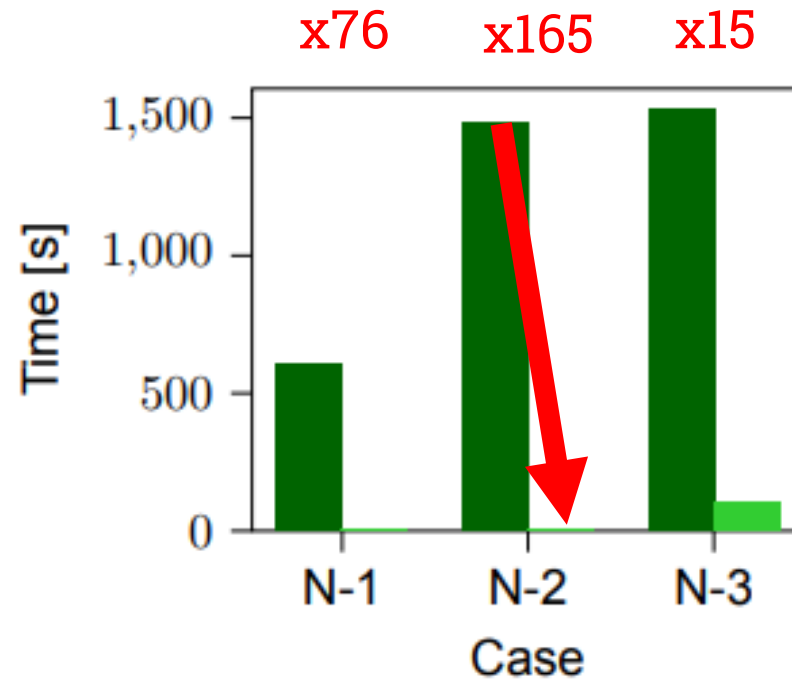
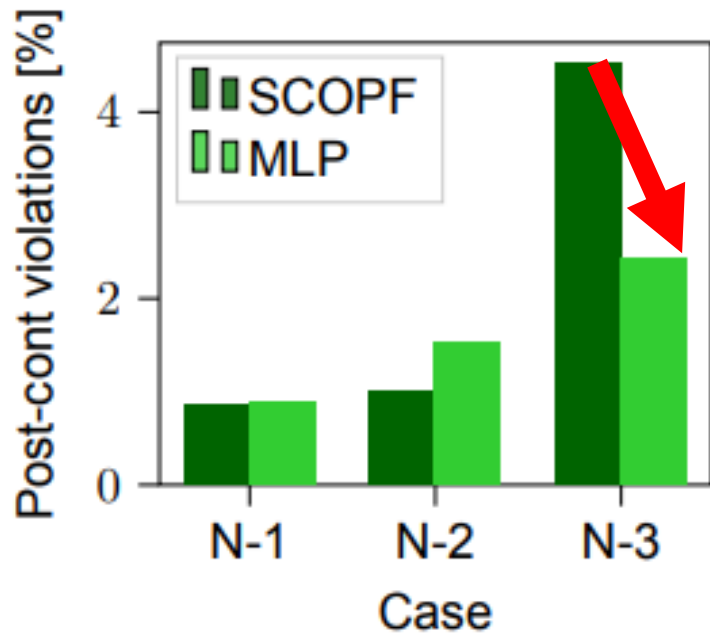


Removing islanding cases

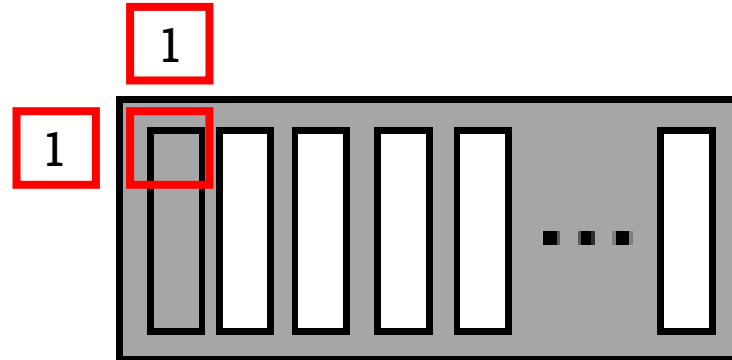


# Performance 118-bus system

Proposed approach  
Baseline

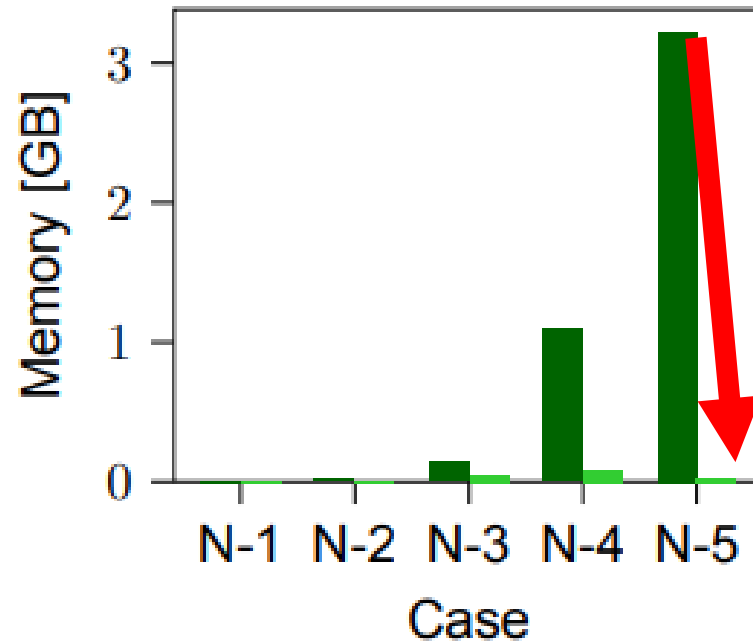
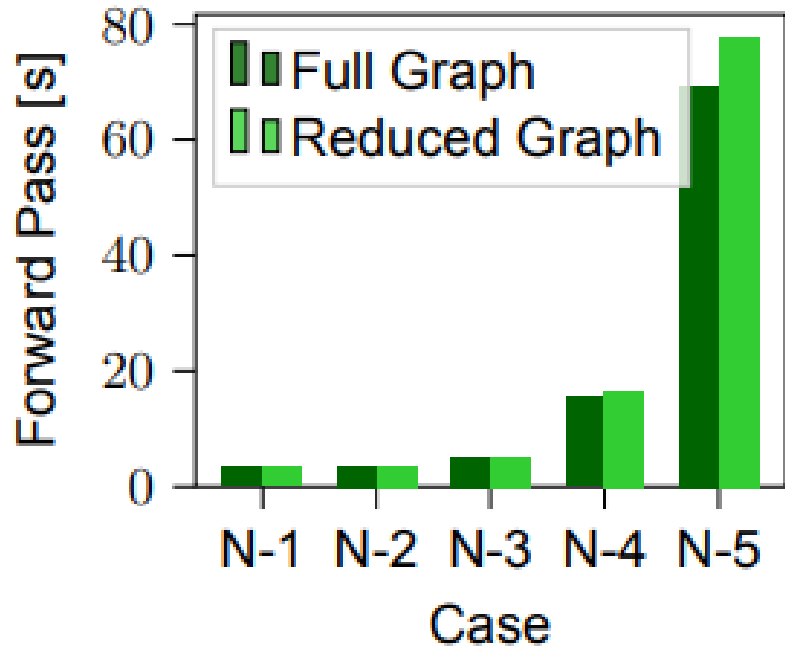


# Sparsity

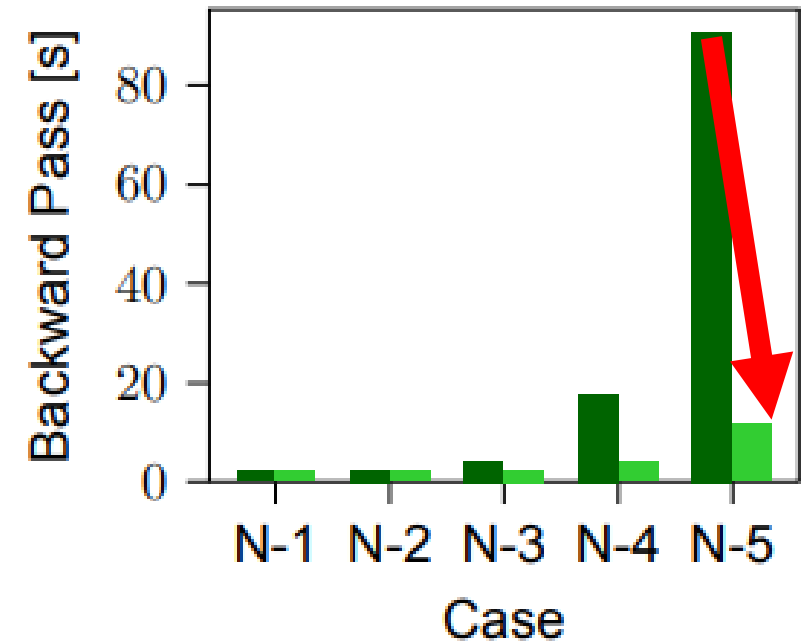


<b>k</b>	<b>1</b>	<b>2</b>	<b>3</b>
39-bus sparsity [%]	98.5	97.6	97.5
118-bus sparsity [%]	99.6	99.3	99.0

# Reducing computational graph



Reduction in memory

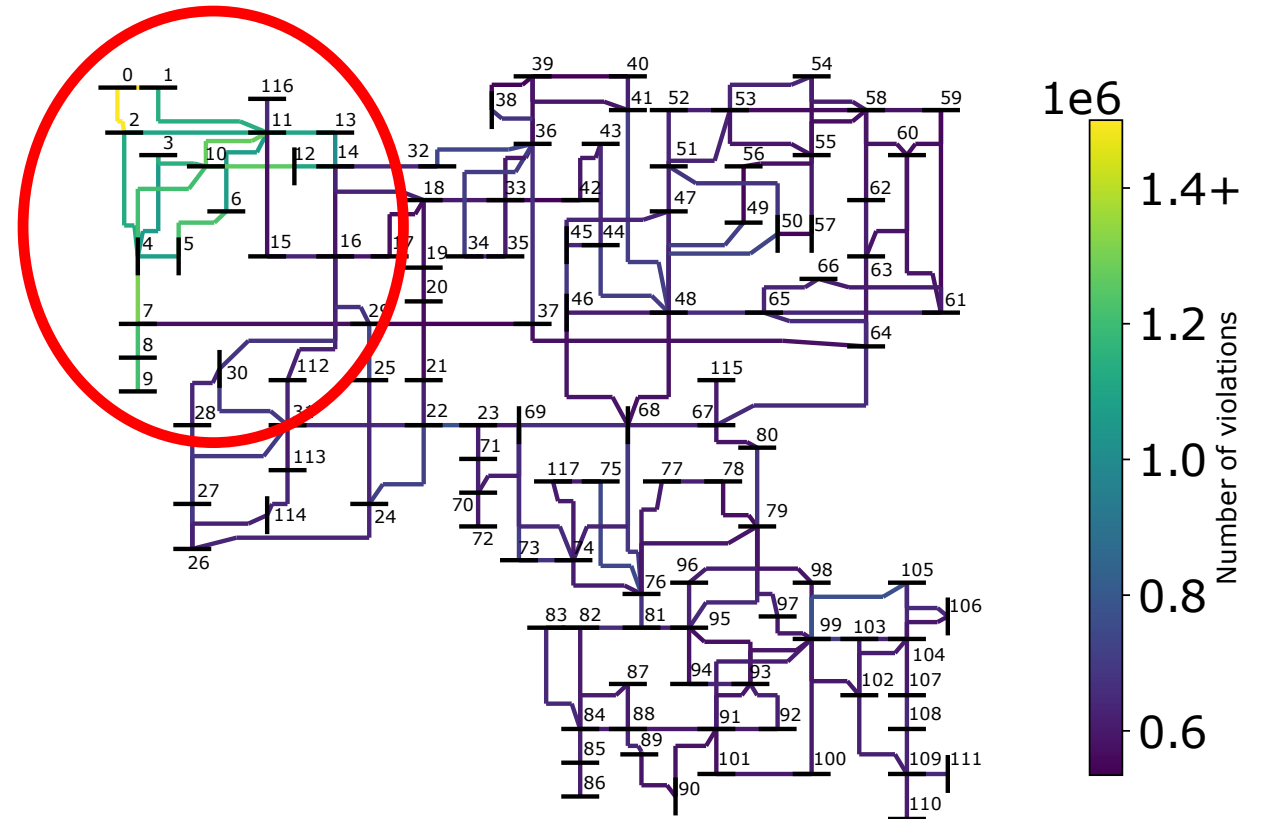
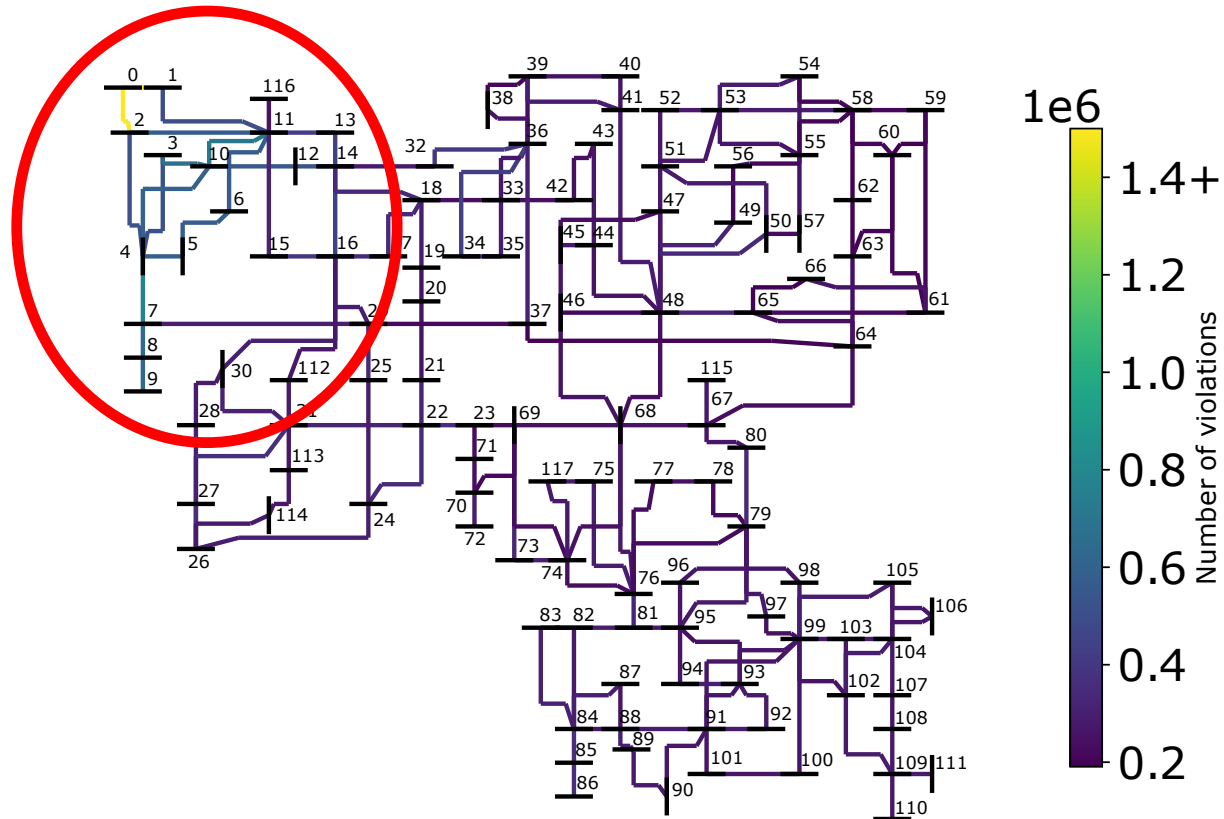


Reduction in computation time

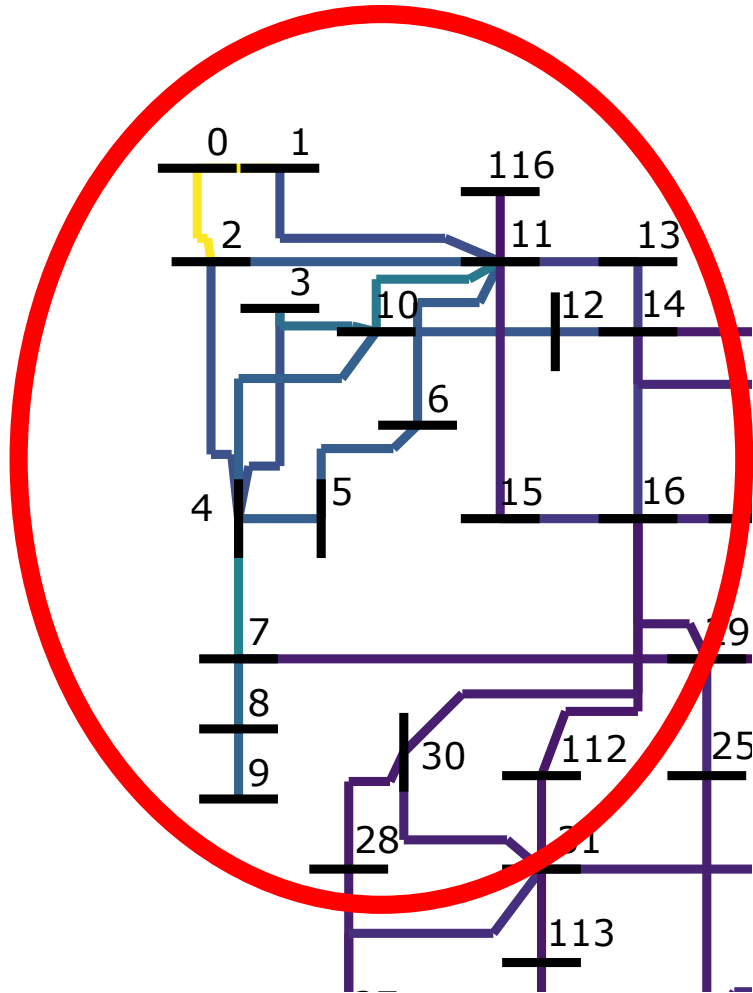
# Physical violations of constraints

N-3 proposed approach

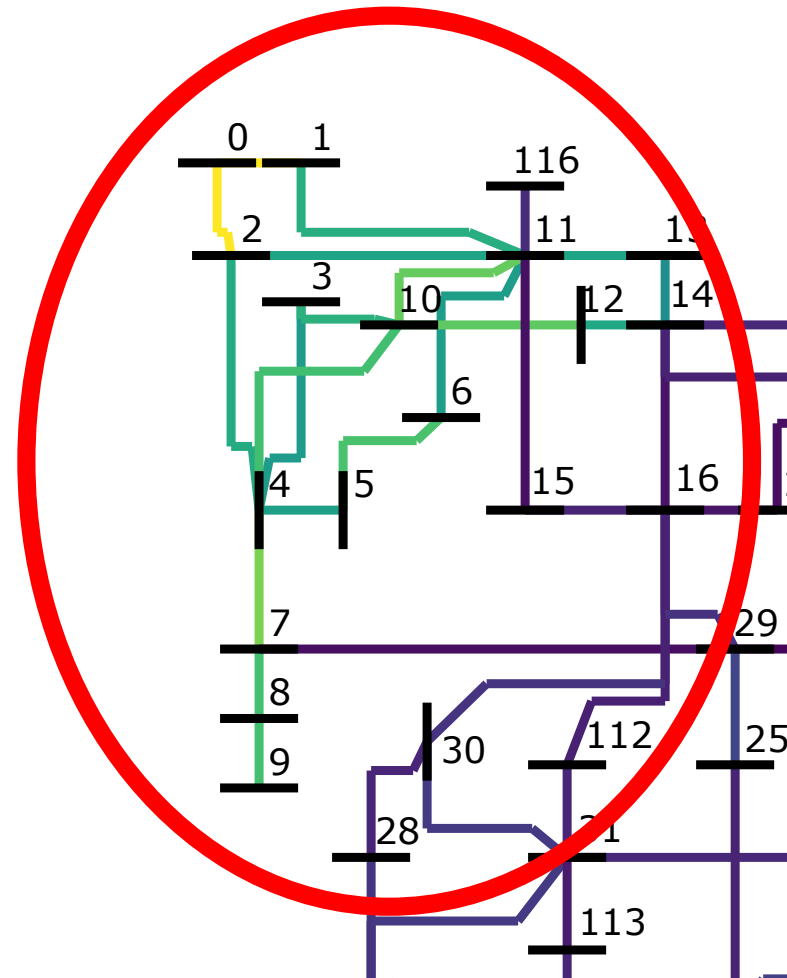
N-3 baseline



N-3 proposed approach

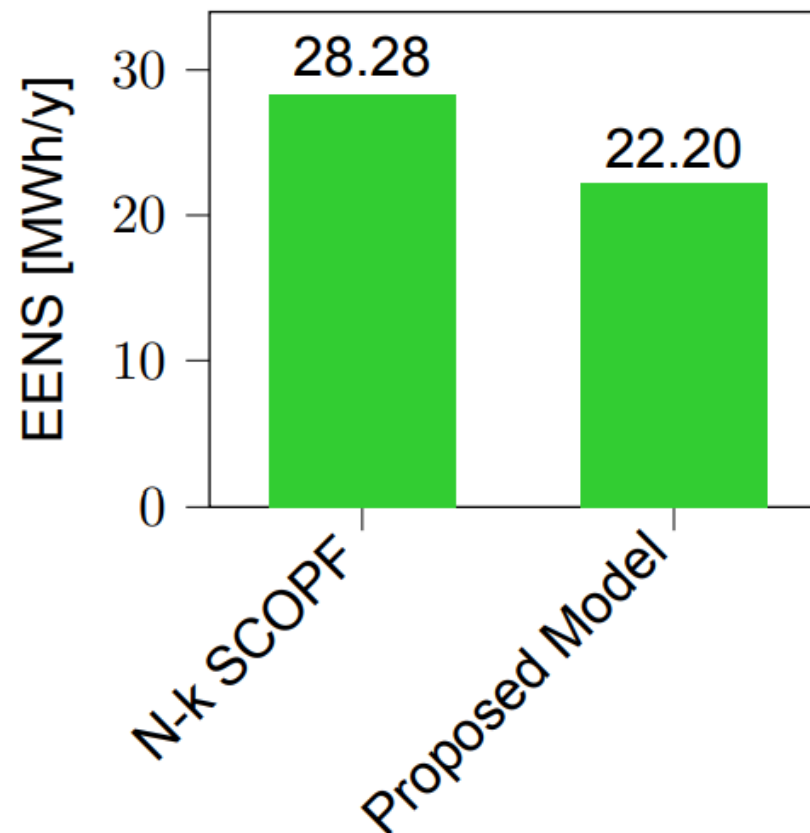
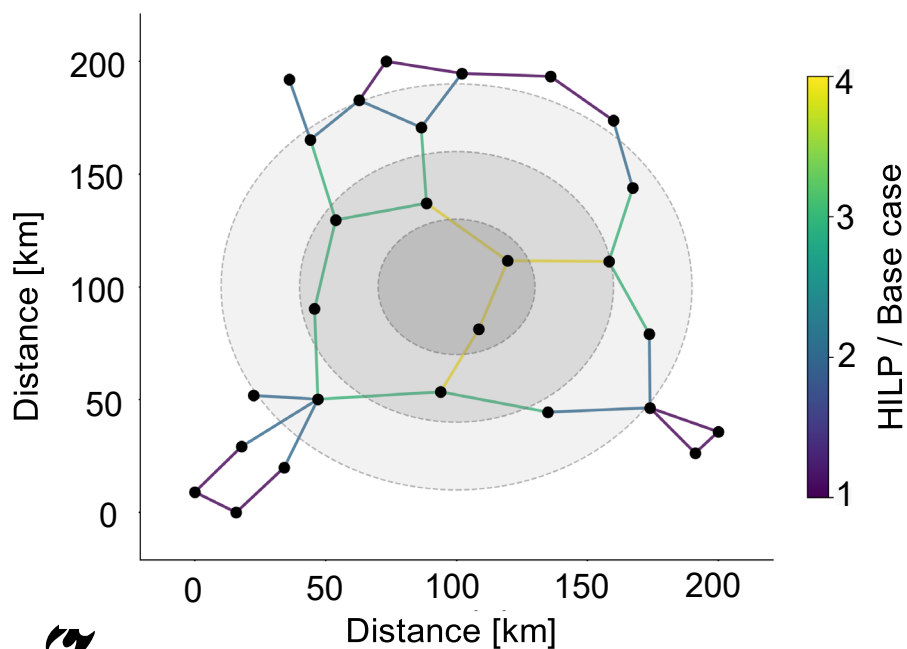


N-3 baseline



# Extreme event

- Individual probabilities change due to earthquake
- Recompute joint probabilities
- Recompute Expected Energy not Served (EENS)

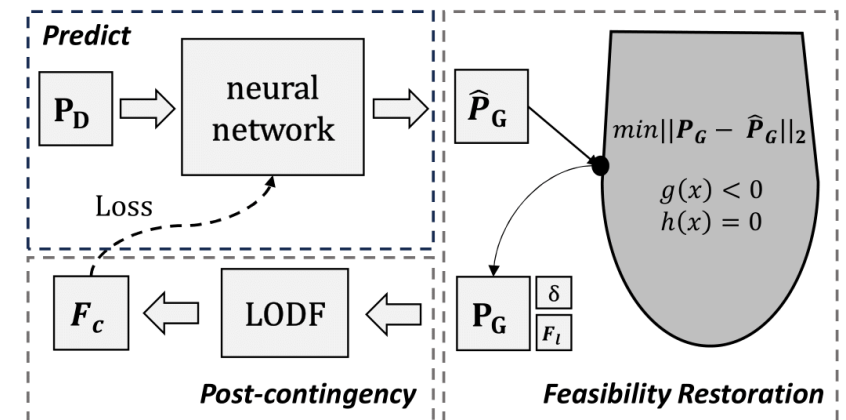


# Conclusion

- Successfully identified many violating post-contingency cases up to the 118-bus N-3 case
  - Significant improvement in computational time
  - Small optimality gap in terms of dispatch cost, if not more optimal
- Probabilistic security assessment shows potential for enhanced reliability and resilience
- **Limitations:** only useful for line overloads, no voltages etc can be checked, changing network topology

# Future work

- Incorporate other equipment outages, which metrics
- Develop for ACOPF
- Corrective approach
- LODF scalability



# Thank you

## Speaker

### Jochen Cremer

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## Team



Bastien Giraud



Ali Rajaei

## Reference

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